

# An ABC interpretation of the multiple auxiliary variable method

by

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## **2 Background**

### **2.1 Auxiliary variable methods**

This is often referred to as the ABC likelihood. It is proportional to a convolution of the likelihood with a uniform density, evaluated at  $y$ . For  $\epsilon > 0$  this is generally an inexact approximation to the likelihood. For discrete data it is possible to use  $\epsilon = 0$  in which case the ABC likelihood equals the exact likelihood, and  $s_{ABC}$  is unbiased.

For MRFs empirically it is observed that, compared with competitors such as the exchange algorithm (Murray et al., 2006), ABC requires a relatively large number of simulations to yield an efficient algorithm (Friel, 2013).

## 3 Derivation

### 3.1 ABC for MRF models

Suppose that the model  $f(y)$  has an intractable likelihood but can be targeted by a MCMC chain  $x = (x_1, x_2, \dots, x_n)$ . Let  $\pi$  represent densities relating to this chain. Then  $\pi_n(y) := \pi(x_n = y)$  is an approximation of  $f(y)$  which can be estimated by ABC. For now suppose that  $y$  is discrete and consider the ABC likelihood estimate requiring an exact match: simulate from  $\pi(x)$  and return  $\pi(x_n = y)$ . We will consider an IS variation on this: simulate from  $g(x)$  and return  $\pi(x_n = y) / g(x)$ . Under the mild assumption that  $g(x)$  has the same support as  $\pi(x)$  (typically true unless  $n$  is small), both estimates have the expectation  $\pi(x_n = y)$ .

This can be generalised to cover continuous data using the identity

$$\pi_n(y) = \int_{x_n=y} \pi(x) dx_{1:n-1};$$

where  $x_{i:j}$  represents  $(x_i, x_{i+1}, \dots, x_j)$ . An importance sampling estimate of this integral is

$$w = \frac{\pi(x)}{g(x_{1:n-1})} \quad (3)$$

where  $x$  is sampled from  $g(x_{1:n-1})$  ( $x_n = y$ ), with  $\delta$  representing a Dirac delta measure. Then, under mild conditions on the support of  $g$ ,  $w$  is an unbiased estimate of  $\pi_n(y)$ .

The ideal choice of  $g(x_{1:n-1})$  is  $\pi(x_{1:n-1} | x_n = y)$ , as then  $w = \pi(x_n = y)$  exactly. This represents sampling from the Markov chain conditional on its state being  $y$ .

### 3.2 Equivalence to MAV

We now show that natural choices of  $\pi(x)$  and  $g(x_{1:n-1})$  in the ABC method just outlined

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Here  $(x_j)$  defines a MCMC chain with transitions  $K_i(x_{i+1}|x_i)$ . Suppose  $K_i$  is as in Section 2.1 for  $i \leq a$ , and for  $i > a$  it is a reversible Markov kernel with invariant distribution  $f(\cdot)$ . Also assume  $b := n - a \rightarrow \infty$ . Then the MCMC chain ends in a long sequence of steps targeting  $f(\cdot)$  so that  $\lim_{n \rightarrow \infty} \pi_n(\cdot) = f(\cdot)$ . Thus the likelihood being estimated converges on the true likelihood for large  $n$ . Note this is the case even for  $x_{n-1}$ .

The importance density  $g(x_{1:n} | y)$  specifies a reverse time MCMC chain starting from  $x_n = y$  with transitions  $K_i(x_i | x_{i+1})$ . Simulating  $x$  is straightforward by sampling  $x_n$ , then  $x_{n-1}$  and so on. This importance density is an approximation to the ideal one stated at the end of Section 3.1.

The resulting likelihood estimator is

$$w = f_1(x_1 | y) \prod_{i=1}^{n-1} \frac{K_i(x_{i+1} | x_i)}{K_i(x_i | x_{i+1})}.$$

Using detailed balance gives

$$\frac{K_i(x_{i+1} | x_i)}{K_i(x_i | x_{i+1})} = \frac{f_i(x_{i+1} | y)}{f_i(x_i | y)} = \frac{\pi_i(x_{i+1} | y)}{\pi_i(x_i | y)},$$

so that

$$w = f_1(x_1 | y) \prod_{i=1}^{n-1} \frac{\pi_i(x_{i+1} | y)}{\pi_i(x_i | y)} = (\pi_1(y)) \prod_{i=2}^n \frac{\pi_{i-1}(x_i | y)}{\pi_i(x_i | y)}.$$

This is an unbiased estimator of  $\pi_1(y)$ . Hence

$$v = \prod_{i=2}^n \frac{\pi_{i-1}(x_i | y)}{\pi_i(x_i | y)} = \prod_{i=2}^{n-a} \frac{\pi_{i-1}(x_i | y)}{\pi_i(x_i | y)}.$$

is an unbiased estimator of  $\pi_1(y) = (\pi_1(y))^{1/Z(\cdot)}$ . In the above we have assumed, as in Section 3.1, that  $\pi_1$  is normalised. When this is not the case then we instead get an estimator of  $Z(\cdot) = Z(\cdot)$ , as for MAV methods. Also note that in either case a valid estimator is produced for any choice of  $y$ .

The ABC estimate can be viewed by a two stage procedure. First run a MCMC chain of length  $b$  with any starting value, targeting  $f(\cdot | y)$

## References

Andrieu, C. and Roberts, G. O. (2009). The pseudo-marginal approach for efficient Monte Carlo computations. *The Annals of Statistics* pages 697{725.